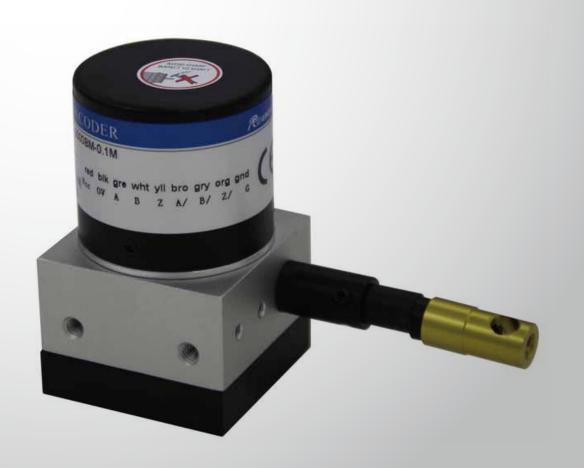
# 产品选型手册

Product selection guide



RLC40D Draw Wire Sensor

#### Digital Signal Output Type



Incremental encoder and absolute encoder are optional for the digital signal output type. Output signals are square wave ABZ signals or Gray code signals. Measurement range is up to 600mm. Linear accuracy: 0.05% FS. Resolution based on the different configuration can reach 0.001mm / pulse in maximum. Working temperature:  $-30\ ^{\circ}$  C-+90  $^{\circ}$  C.

#### Part Number 600 **RLC** 40 Box Size Measuring Range **Operating Voltage** Cable Length 40\*40mm 0-600mm 1:5V Standard 1M 2:8-26V **Draw Wire Output Signal Output Type** Resolution (mm) **Sensor Series** Digital Output A: 0.05 Incremental E: Voltage B: 0.025 Encoder Type F: Pushpull C: 0.02 C: Open Collector D:0.01 L: Line Driver (5V) E:0.008 A: Wide Voltage Line Driver (8-26V)

#### Mechanical Specifications

Measuring Range	0——600mm optional				
	Aluminium alloy, oxidation surface treating, wear and				
Housing					
	corrosion prevention				
Wire Rope	0.6mm high flexible				
	imported plastic coated				
	wire rope				
Wire retraction force (min)	appr. 1N				
Wire extension force (max)	appr. 2.5N				
Linear Accuracy	0.05%FS				
Repeatability Accuracy	0.01%				
Life	>10 million times				

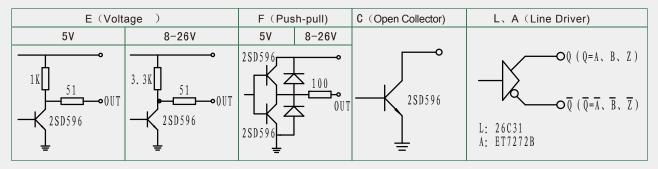
#### Electrical Specifications

Sensor Element	Incremental Encoder						
Electrical Connection	Cable Radial, 1m						
Output Model	Voltage	Push-Pull	Open Collector	Line Driver (5V)	Wide Voltage Line Driver (8-26V)		
Operating Voltage	DC5V/8-26V						
Sensor Resolution(mm)	0.05	0.025	0.02	0.01	0.008		
Encoder Resolution (ppr)	1000	2000	2500	3600	5000		
Max. Reciprocating Speed	1000mm/s						
Reciprocating Frequence	50 Hz(See Reciprocating Amplitude)						

### Environmental Specifications

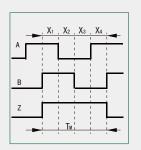
Temperature Range	-30°C90°C
Vibration Resistance	10HZ1500HZ 10G
Protection Class	IP54(Standard)
Weight(kg)	0.255

#### Output Circuit

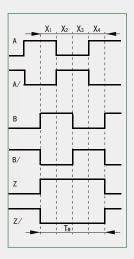


Note: C, F output provide ground protection diode

#### Output Waveform



Waveform for C, E, F output



Waveform for L, A output

Wave Ratio :  $X1+X2=0.5T\pm0.1T$ 

X2+X3=0. 5T  $\pm$  0. 1T

Phase Different : Xn≥0.125T (n=1, 2, 3, 4)

Absolute Angle Error:  $\leqslant$ 0.2T

Cycle Error  $: \leqslant 0.05T$ 

 $T=360^{\circ}$  / N (N=lines count per revolution)

Width of Z signal

 $1 \cdot Tm=1T\pm 0.5T$ 

 $Tm=nT\pm0.1T (n\geqslant2)$ 

The phase relationship of Z signal and A, B signal is not stipulated.

2 、 Tm=0.5T $\pm$ 0.25T

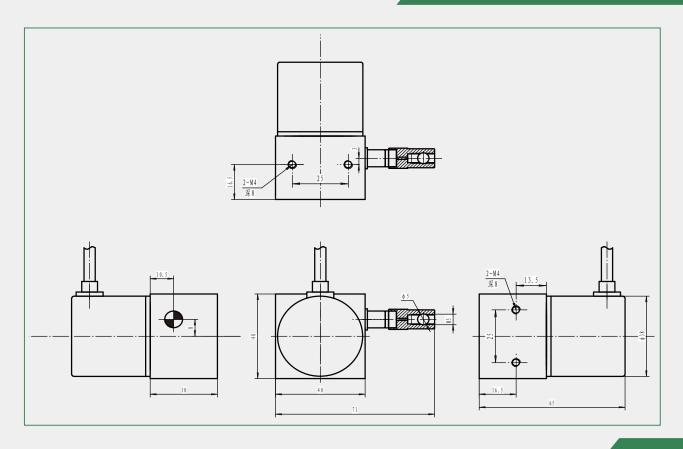
Tm=0.  $25T\pm0$ . 125T

Tm=0.  $25T\pm0$ . 125T

The picture shows the clockwise (CW) waveform from the shaft side.

Cable Color	Red	Yellow	White	Black	Green	Grey	Brown	Orange	Shield
Line Driver	Vcc	Z	В	OV	Α	B/	A/	Z/	G
Voltage	Vcc	Z	В	OV	Α	-	-	-	G
Open Colletor	Vcc	Z	В	OV	Α	-	-	-	G
Push-pull	Vcc	Z	В	OV	А	-	-	-	G

## Mechanical Drawings



Notes

- 1.Damage may occur if wire is released and allowed to retract without tension.
- 2. Make certain the wire path is clear of objects or sharp edges to prevent wire damage.
- 3. Wire should exit as straight as possible. A pulley may be used to redirect it.
- 4.Please connect the cable according to the specifications of electrical connections. Make sure the connections are correct when power is on.
- 5.Draw wire sensor is a precision instrument. Knocking is forbidden.

  Please ensure the cleanness of the equipment and wire to prolong the service life.
- 6. Avoid external force on wire.
- 7.Do not self-dismantle for that the strong spring inside the sensor may hurt you.

